T.	Hits	Search Text	DB.	Time atoms
Number	nits	Search lext	DB	Time stamp
1	70	(pet near3 robot) and sony	USPAT;	2004/01/23
2	43	(pet near3 robot) and sony and (voice	US-PGPUB USPAT;	07:49 2004/01/23
		speech)	US-PGPUB	07:49
-	0	704/272.ccls. and (behavior with speech)	USPAT;	2004/01/20
		and (behavior with (touch pressure)) and prosody	US-PGPUB; EPO; JPO;	10:55
		prosody	DERWENT	
-	0	704/\$.ccls. and (behavior with speech)	USPAT;	2004/01/20
		and (behavior with (touch pressure)) and prosody	US-PGPUB; EPO; JPO;	10:55
		prosouy	DERWENT	
_	0	(behavior with speech) and (behavior with	USPAT;	2004/01/20
		(touch pressure)) and prosody	US-PGPUB;	10:55
			EPO; JPO; DERWENT	
-	0	, the state of the	USPAT;	2004/01/20
		(touch pressure)) and prosody	US-PGPUB;	10:56
			EPO; JPO; DERWENT	
-	0	behavior and(touch pressure) and prosody	USPAT;	2004/01/20
		and 704/272.ccls.	US-PGPUB;	10:56
			EPO; JPO; DERWENT	
-	19	behavior and (touch pressure) and prosody	USPAT;	2004/01/20
		and 704/\$	US-PGPUB;	11:01
			EPO; JPO; DERWENT	
-	0	behavior and (touch pressure) and prosody	USPAT;	2004/01/20
		and 446/\$.ccls.	US-PGPUB;	11:02
			EPO; JPO; DERWENT	
-	0	response and (touch pressure) and prosody	USPAT;	2004/01/20
		and 704/272.ccls.	US-PGPUB; EPO; JPO;	11:02
			DERWENT	
-	214	response and (touch pressure) and prosody	USPAT;	2004/01/20
Ì		and 704/275.ccls. 704/272.ccls.	US-PGPUB; EPO; JPO;	11:02
			DERWENT	
-	11	response and (touch pressure) and prosody	USPAT;	2004/01/20
		and 704/275.ccls. 704/272.ccls. and robot	US-PGPUB; EPO; JPO;	11:04
			DERWENT	
-	0	response and (touch pressure) and prosody	USPAT;	2004/01/20
		and 704/275.ccls. and 704/272.ccls. and robot	US-PGPUB; EPO; JPO;	11:05
			DERWENT	
-	2	response and(touch pressure) and prosody and (704/275.ccls. 704/272.ccls.) and	USPAT;	2004/01/20
		robot	US-PGPUB; EPO; JPO;	11:05
			DERWENT	
-	9	response and(touch pressure) and prosody and (704/\$.ccls.) and robot	USPAT;	2004/01/20
		and (103/9.CCIS.) and IODOL	US-PGPUB; EPO; JPO;	11:19
			DERWENT	
-	14	response and(touch pressure) and prosody and robot	USPAT;	2004/01/20
			US-PGPUB; EPO; JPO;	11:10
			DERWENT	
-	14	(behavior response action) and(touch pressure) and prosody and robot	USPAT; US-PGPUB;	2004/01/20 11:10
		product, and product and robot	EPO; JPO;	11.10
	[		DERWENT	
_	21	(behavior response action) and(touch pressure) and prosody and (toy robot	USPAT; US-PGPUB;	2004/01/20 13:03
		"novelty item")	EPO; JPO;	13.03
			DERWENT	

- ;	2	6160986.pn.	USPAT; US-PGPUB;	2004/01/20 11:12
			EPO; JPO; DERWENT	
_	21	(touch pressure) and prosody and (toy robot "novelty item")	USPAT; US-PGPUB;	2004/01/20 11:19
			EPO; JPO; DERWENT	
-	44	prosody and (toy robot "novelty item")	USPAT; US-PGPUB;	2004/01/20 11:14
			EPO; JPO; DERWENT	
-	261	(touch pressure) and emotion and (toy	USPAT;	2004/01/20
		robot "novelty item")	US-PGPUB; EPO; JPO;	11:19
_	17	response and(touch pressure) and emotion	DERWENT USPAT;	2004/01/20
		and (704/\$.ccls.) and robot	US-PGPUB; EPO; JPO;	11:22
_	56	response and/tough programs) and emotion	DERWENT	2004/01/20
	30	response and(touch pressure) and emotion and (toy robot) and dictionary	USPAT; US-PGPUB;	2004/01/20 11:24
			EPO; JPO; DERWENT	
-	210	response and (touch pressure) and emotion and (toy robot)	USPAT; US-PGPUB;	2004/01/20 14:39
		•	EPO; JPO; DERWENT	
-	67	response and (touch pressure) and emotion	USPAT;	2004/01/20
		and (pet near3 robot)	US-PGPUB; EPO; JPO;	11:41
_	79	"pet robot" and emotion	DERWENT USPAT;	2004/01/20
			US-PGPUB; EPO; JPO;	11:46
_	31	"pet robot" and emotion and (recogn\$6	DERWENT USPAT;	2004/01/20
:		near4 (speech voice))	US-PGPUB; EPO; JPO;	12:14
	120	Unabatili and Januarda and M	DERWENT	0004/04/00
	130	"robot" and (prosody prosodic emotion) and (recogn\$6 near4 (speech voice))	USPAT; US-PGPUB;	2004/01/20 12:28
			EPO; JPO; DERWENT	
-	30	(toy robot pet "novelty item") and (detect\$4 near4 (prosody prosodic	USPAT; US-PGPUB;	2004/01/20 12:57
		emotion)) and (recogn\$6 near4 (speech voice))	EPO; JPO; DERWENT	
_	10	interactive near3 pet near3 robot	USPAT; US-PGPUB;	2004/01/20
			EPO; JPO;	12.50
-	11	("4657104"   "5465525"   "5903988"	DERWENT USPAT	2004/01/20
		"5963712"   "6038493"   "6058385"   "6134580"   "6234902"   "6275773"		12:59
_	63	"6282460"   "6321140").PN. (behavior response action) and(touch	USPAT;	2004/01/20
		pressure) and prosody	US-PGPUB; EPO; JPO;	13:02
_	21	(behavior response action) and(touch	DERWENT USPAT;	2004/01/20
		pressure) and prosody and (pet toy robot "novelty item")	US-PGPUB;	13:04
	240	-	EPO; JPO; DERWENT	0004455455
-	340	(behavior response action) and(touch pressure) and emotion and (pet toy robot	USPAT; US-PGPUB;	2004/01/20   13:04
		"novelty item")	EPO; JPO; DERWENT	
-	118	<pre>(behavior response action) and((touch pressure) near4 (sensor dector)) and</pre>	USPAT; US-PGPUB;	2004/01/20
		emotion and (pet toy robot "novelty item")	EPO; JPO; DERWENT	
		<u> </u>		<u> </u>

Search History

1/23/04 8:59:21 AM

-•	2	6415439.pn.	USPAT; US-PGPUB;	2004/01/20 13:25
-	1	2002/0049833	EPO; JPO; DERWENT USPAT; US-PGPUB;	2004/01/20 13:27
_	0	"2002/0049833".PN.	EPO; JPO; DERWENT USPAT	2004/01/20
_	0	"2002/0049833".PN.	USPAT	13:25 2004/01/20
_	15	,	USPAT	13:26 2004/01/20
-	0	"5745884"   "5771273"   "5794221"   "5802283"   "5884262"   "5889845"   "5995138"   "6028917"   "6031975"   "6243450"   "6292478"   "6314169"   "2002/0049833").PN. kikinis and 719/219.ccls.	USPAT; US-PGPUB;	13:26 2004/01/20 13:27
-	303	kikinis near3 dan	EPO; JPO; DERWENT USPAT; US-PGPUB;	2004/01/20 13:49
-	2	toshihiro and (pet near3 robot)	EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	2004/01/20 13:49
-	42	(action response behavior) and (touch pressure) and emotion and (toy robot) and (704/275.ccls. 704/272.ccls. 704/231.ccls. 700/248.ccls. 700/243.ccls. 318/568.12.ccls. 704/209.ccls.	DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 14:51
-	174	704/207.ccls. 704/270.ccls.) (action response behavior) and (touch pressure) and (detect\$5 emotion) and (toy robot) and (704/275.ccls. 704/272.ccls. 704/231.ccls. 700/248.ccls. 700/243.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 14:52
-	18	pressure) and (detect\$5 near5 emotion) and (toy robot) and (704/275.ccls. 704/272.ccls. 704/231.ccls. 700/248.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 15:09
-	19	near5 emotion) and (pet toy robot) and (704/275.ccls. 704/272.ccls. 704/231.ccls. 700/248.ccls. 700/243.ccls. 318/568.12.ccls. 704/209.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 15:17
-	59	704/207.ccls. 704/270.ccls.) (action response behavior) and (detect\$5 near5 emotion) and (pet toy robot)	USPAT; US-PGPUB; EPO; JPO;	2004/01/20 15:34
-	5	(action response behavior) and (detect\$5 near5 emotion) and (electronic near3 pet)	DERWENT USPAT; US-PGPUB; EPO; JPO;	2004/01/20 15:35
-	163	sony and (pet near3 robot)	DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 15:35
-	14	(robot toy) and (transition near3 probability) and dictionary	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 10:48

_?	104	<pre>(robot toy) and (transition near3 probability)</pre>	USPAT; US-PGPUB;	2004/01/22 10:57
			EPO; JPO;	
	_	<u> </u>	DERWENT	
-	2	(robot toy) and (probability near3	USPAT;	2004/01/22
		automaton) and (dictionary)	US-PGPUB;	10:58
			EPO; JPO;	
	4	(	DERWENT	2004/01/22
-	4	(probability near3 automaton) and (dictionary)	USPAT; US-PGPUB;	2004/01/22 11:02
		(dictionary)	EPO; JPO;	11:02
			DERWENT	
-	43	(toy robot) and (HMM) and (dictionary)	USPAT;	2004/01/22
		(***], (*****) (******************	US-PGPUB;	11:02
			EPO; JPO;	
			DERWENT	
-	3196	robot and (transition probability)	USPAT	2004/01/22
				15:49
-	30	robot and (transition near3 probability)	USPAT	2004/01/22
				15:49
-	16	robot and (transition near3 probability)	USPAT	2004/01/22
_		and automaton	HCDAM	15:53
1 -	4	toy and (transition near3 probability) and automaton	USPAT	2004/01/22
_	39	and automaton   (transition near3 probability) and	USPAT	15:53   2004/01/22
		automaton	OSEKI	15:54
-	415	(algorithm near4 sequence) and robot	USPAT;	2004/01/22
		, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	US-PGPUB;	15:55
			EPO; JPO;	
			DERWENT	
-	1	(algorithm near4 sequence near4 action)	USPAT;	2004/01/22
		and robot	US-PGPUB;	15:55
			EPO; JPO;	
	,		DERWENT	
-	1	(algorithm near4 sequence with action)	USPAT;	2004/01/22
		and robot	US-PGPUB;	15:56
			EPO; JPO; DERWENT	
_	6	(algorithm near4 sequence) and robot and	USPAT;	2004/01/22
		automaton	US-PGPUB;	15:57
			EPO; JPO;	
			DERWENT	
-	44	(algorithm near4 sequence) and toy	USPAT;	2004/01/22
			US-PGPUB;	16:14
			EPO; JPO;	
	_	/	DERWENT	0004/01/00
-	0	(automation near4 probablility) and	USPAT;	2004/01/22
		CTANSICION	US-PGPUB; EPO; JPO;	16:14
			DERWENT	
_	0	automation near4 probablility	USPAT;	2004/01/22
		promote in the promot	US-PGPUB;	16:14
			EPO; JPO;	
			DERWENT	
-	0	sequence near4 probablility	USPAT;	2004/01/22
			US-PGPUB;	16:15
			EPO; JPO;	
	1240	(appropriate touties as a second	DERWENT	0004/01/00
-	1249	(sequence with (action response)) and robot	USPAT;	2004/01/22
			US-PGPUB;	16:16
			EPO; JPO; DERWENT	
_	86	(sequence with (action response)) and	USPAT;	2004/01/22
		robot and dictionary	US-PGPUB;	16:20
		<b>-</b>	EPO; JPO;	
			DERWENT	
-	619	(sequence with (action response)) and toy	USPAT;	2004/01/22
			US-PGPUB;	16:21
			EPO; JPO;	
			DERWENT	

-•	45	(sequence with (action response)) and toy	USPAT;	2004/01/22
1'		and dictionary	US-PGPUB;	16:21
			EPO; JPO;	
			DERWENT	
-	0	(probability with sequence with (action	USPAT;	2004/01/22
į		response)) and toy and dictionary	US-PGPUB;	16:21
			EPO; JPO;	
			DERWENT	
-	1	(probability same sequence with (action	USPAT;	2004/01/22
		response)) and toy and dictionary	US-PGPUB;	16:22
			EPO; JPO;	
			DERWENT	
-	11	(F==== // Lame = -4	USPAT;	2004/01/22
		response)) and (toy robot)	US-PGPUB;	16:24
			EPO; JPO;	
			DERWENT	
-	2	(probability same sequence with	USPAT;	2004/01/22
		(behavior)) and (toy robot)	US-PGPUB;	16:25
			EPO; JPO;	
			DERWENT	
-	166992	autonomous adaptation	USPAT;	2004/01/22
			US-PGPUB;	16:26
			EPO; JPO;	
			DERWENT	
-	12	autonomous near3 adaptation	USPAT;	2004/01/22
			US-PGPUB;	16:37
			EPO; JPO;	
			DERWENT	
-	9	shibata and (pet near3 robot)	USPAT;	2004/01/22
			US-PGPUB;	16:37
			EPO; JPO;	
			DERWENT	